

# AUTOMATED TRAFFIC SIGNAL PERFORMANCE MEASURES

TEXITE SPRING MEETING – MAY 30, 2014

Jamie Mackey, Utah DOT





## Helping Traffic Engineers Manage Data to Make Better Decisions

# Automated Traffic Signal Performance Measures

BY DARCY BULLOCK, P.E., ROB CLAYTON, P.E., PTOE, JAMIE MACKEY, P.E., STEVE MISGEN, P.E., PTOE, AMANDA STEVENS, P.E., JIM STURDEVANT, P.E., AND MARK TAYLOR, P.E., PTOE

Improved signal operations with smooth and equitable traffic flow are goals for most traffic engineers; however the limited snapshot-view retiming methods that involve manual data collection, traffic signal modeling, and field fine-tuning are resource intensive and unresponsive to changes in traffic patterns. The National Transportation Operations Coalition's 2012 National Traffic Signal Report Card has led agencies to focus resources on these activities and develop methodologies to examine all the components of traffic signal operations.<sup>1</sup> These data-driven program management plans provide objective methods for identifying shortcomings and encourages coordination with neighboring jurisdictions. In addition, agencies need tools to prioritize activities when resources are constrained.



Institute of Transportation Engineers

BOOKSTORE

EMPLOYMENT CENTER

TECHNICAL INFORMATION

ABOUT ITE

JOIN ITE TODAY!

COUNCILS

Automated Traffic Signal Performance Measures



## Learning Hub



Institute of Transportation Engineers

TITLE: **ACHIEVE YOUR AGENCY'S MEASURES-----**

DATE: Wednesday, April 9, 2014

TIME: 12:00 p.m. - 1:30 p.m. East

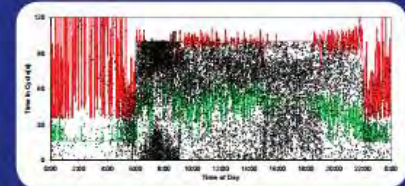


**PURDUE**  
UNIVERSITY



# PERFORMANCE MEASURES FOR TRAFFIC SIGNAL SYSTEMS

*An Outcome-Oriented Approach*



Christopher M. Day, Darcy M. Bullock, Howell Li, Stephen M. Remias, Alexander M. Hainen,  
Richard S. Freije, Amanda L. Stevens, James R. Sturdevant, and Thomas M. Brennan



**PURDUE**  
UNIVERSITY



# SPM Basic Concept

## Automated Data Collection

- Signal controller
- Probe source



## Useful Information about Performance

- Signal
- Corridor
- System

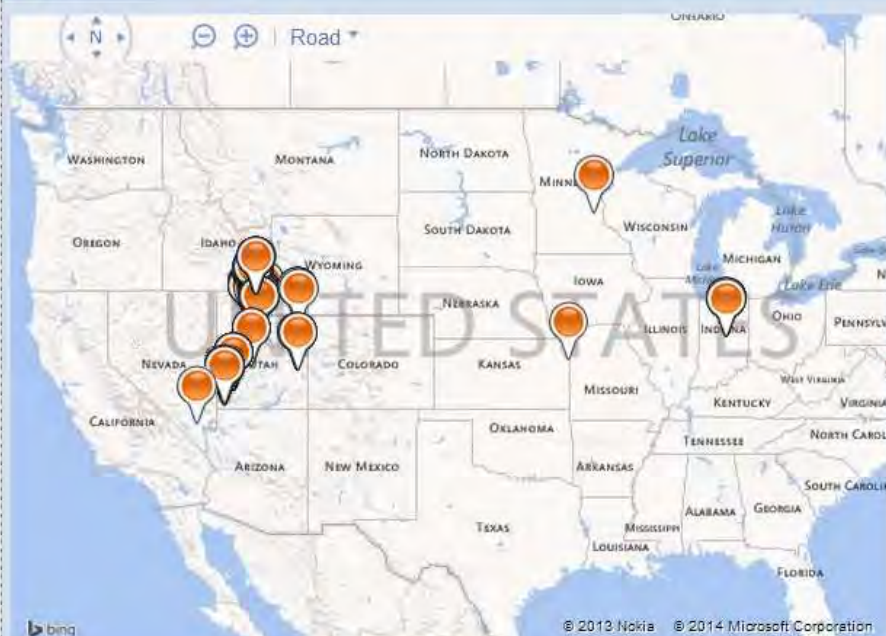


Selected Signal  
 5600 West SR-201 Westbound

Signals  
 Region   
 Metric Type   
 Filter

## Signal List

## Map



## Metric Settings

Metric Type

- ☐ Approach Delay
- ☐ Approach Volume
- ☐ Arrivals On Red
- ☐ Purdue Coordination Diagram
- ☐ Purdue Phase Termination
- ☐ Speed
- ☒ Split Monitor

Y Axis Maximum

Percentile Split

☒ Show Plan Stripes ☒ Show % Max Out/ Force Off  
☒ Show Ped Activity ☒ Show Percent Gap Outs  
☒ Show Average Split ☒ Show Percent Skip  
☒ Upload Current Data

## Dates

Start Date

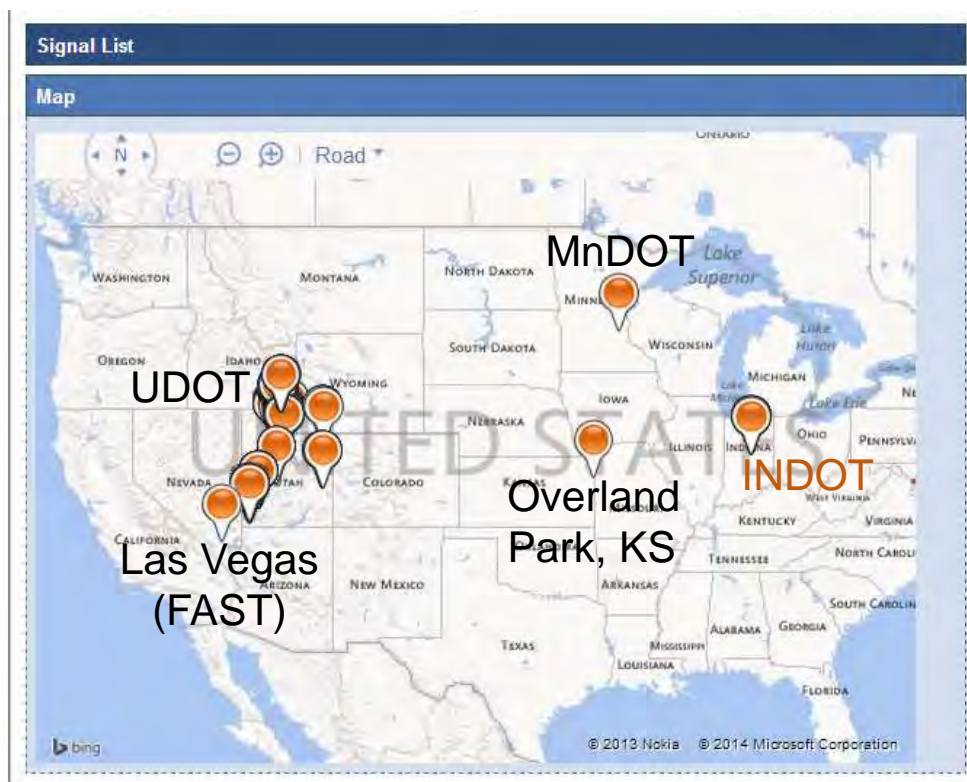
End Date

Reset Date  May 2014

Sun	Mon	Tue	Wed	Thu	Fri	Sat
27	28	29	30	1	2	3
4	5	6	7	8	9	10
11	12	13	14	15	16	17
18	19	20	21	22	23	24
25	26	27	28	29	30	31
1	2	3	4	5	6	7

Create Metrics

## Agencies using UDOT software for SPMs



Create Metrics

Y Axis Maximum

Percentile Split

☒ Show Plan Stripes
 ☒ Show % Max Out/ Force Off

☒ Show Ped Activity
 ☒ Show Percent Gap Outs

☒ Show Average Split
 ☒ Show Percent Skip

☒ Upload Current Data

**Dates**

Start Date   AM

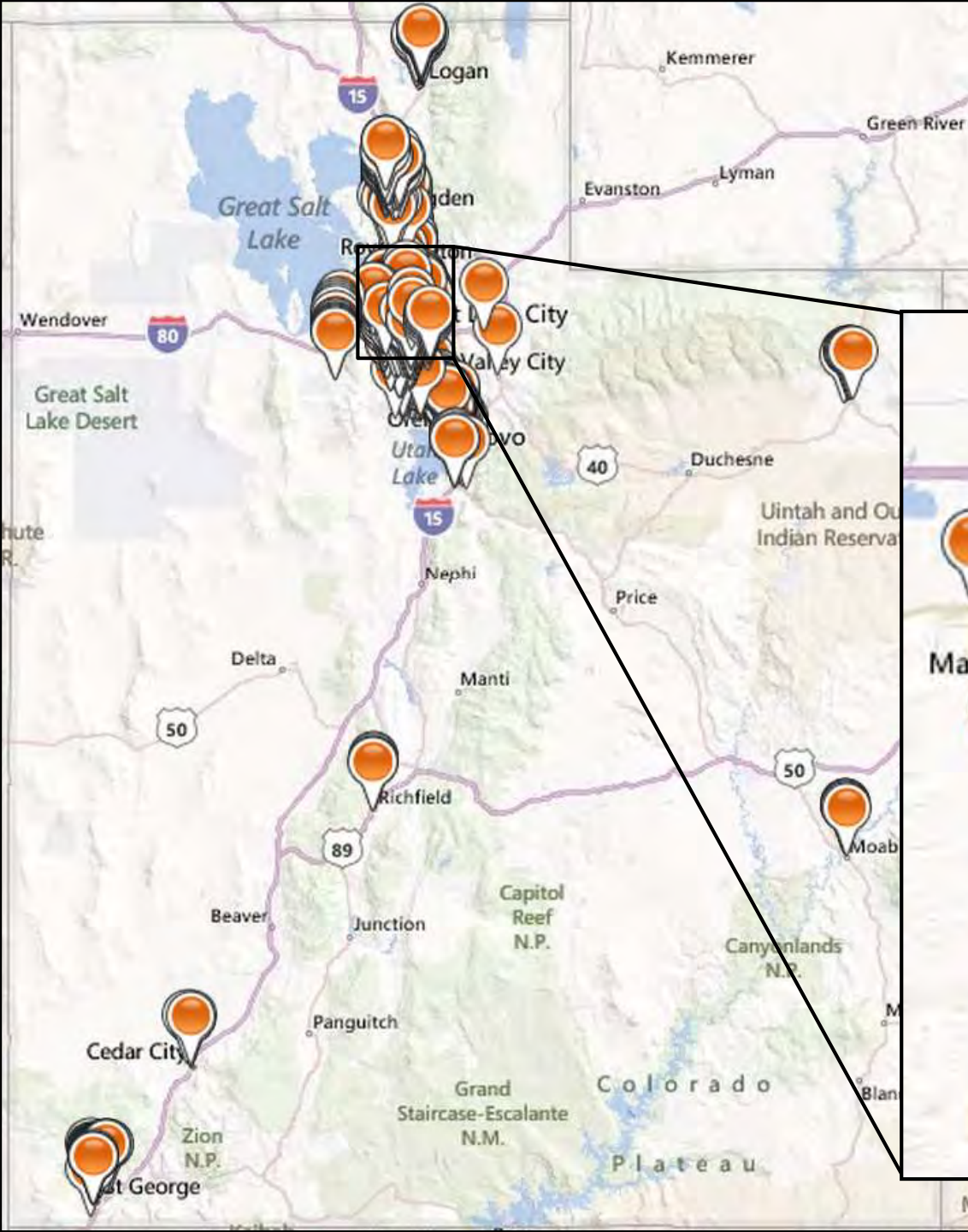
End Date   PM

Reset Date

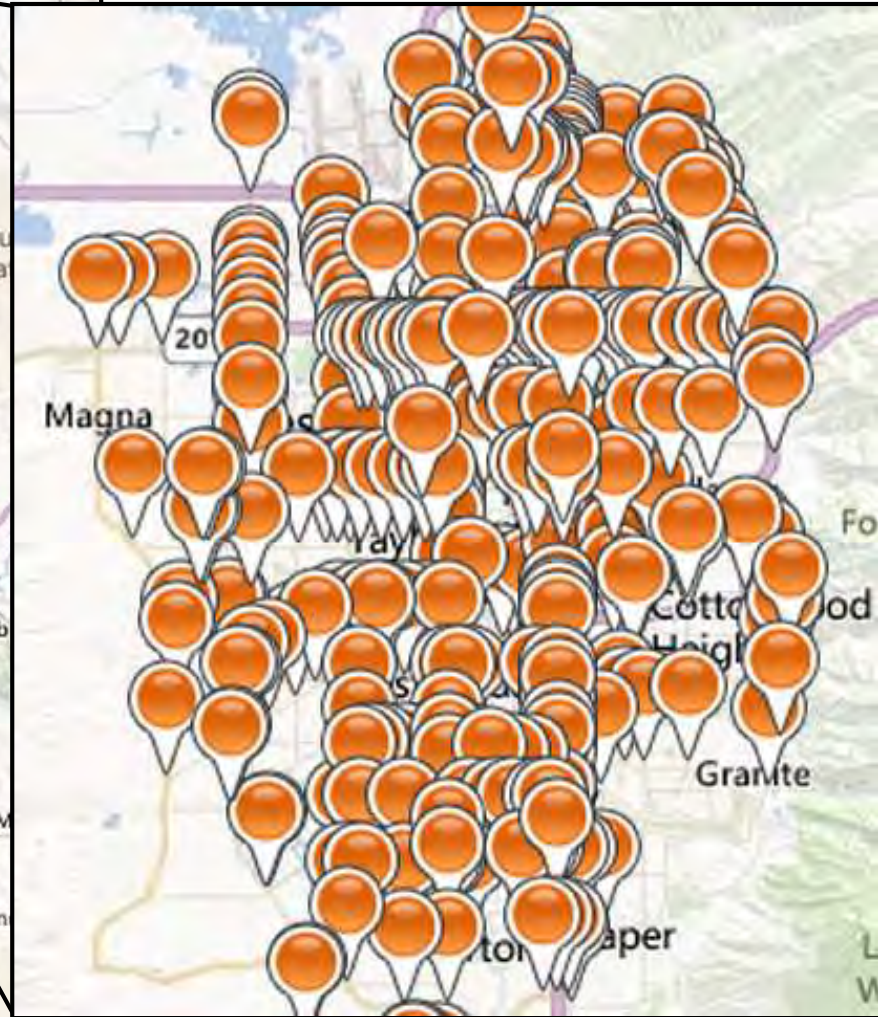
Sun	Mon	Tue	Wed	Thu	Fri	Sat
27	28	29	30	1	2	3
4	5	6	7	8	9	10
11	12	13	14	15	16	17
18	19	20	21	22	23	24
25	26	27	28	29	30	31
1	2	3	4	5	6	7

<http://udottraffic.utah.gov/signalperformancemetrics>





## Salt Lake Valley



# System Requirements



**High-resolution Controller**



**Communications**

Can be done independent of a  
**Central System!**

3) Store in Database

**Server**

**Website**

**Detection**  
(optional)



# Controller Enumerations

## Active Phase Events:

0	Phase On
1	Phase Begin Green
2	Phase Check
3	Phase Min Complete
4	Phase Gap Out
5	Phase Max Out
6	Phase Force Off
7	Phase Green Termination
8	Phase Begin Yellow Clearance
9	Phase End Yellow Clearance
10	Phase Begin Red Clearance
11	Phase End Red Clearance

## Detector Events:

81	Detector Off
82	Detector On
83	Detector Restored
84	Detector Fault- Other
85	Detector Fault- Watchdog Fault
86	Detector Fault- Open Loop Fault

## Preemption Events:

101	Preempt Advance Warning Input
102	Preempt (Call) Input On
103	Preempt Gate Down Input Received
104	Preempt (Call) Input Off
105	Preempt Entry Started

# High-resolution Data

**Detector 5 ON**

**Phase 8 GREEN**

**Detector 5 OFF**

Timestamp	Event Code	Event Parameter
6/27/2013 1:29:51.1	10	8
6/27/2013 1:29:51.1	82	5
6/27/2013 1:29:52.2	1	2
6/27/2013 1:29:52.2	1	6
6/27/2013 1:29:52.3	82	2
6/27/2013 1:29:52.8	82	4
6/27/2013 1:29:52.9	81	4
6/27/2013 1:29:53.3	81	6
6/27/2013 1:29:54.5	81	2
6/27/2013 1:30:02.2	8	2
6/27/2013 1:30:02.2	8	6
6/27/2013 1:30:02.2	33	2
6/27/2013 1:30:02.2	33	6
6/27/2013 1:30:02.2	32	2
6/27/2013 1:30:02.2	32	6
6/27/2013 1:30:06.1	10	2
6/27/2013 1:30:06.1	10	6
6/27/2013 1:30:08.1	1	8
6/27/2013 1:30:13.1	32	8
6/27/2013 1:30:15.8	81	5
6/27/2013 1:30:18.5	82	6
6/27/2013 1:30:27.5	81	6
6/27/2013 1:30:30.4	8	8

# Performance Metrics Uses

## ► Daily Operations

- Basic parameters
- Detection problems
- Complaint response/troubleshooting
- Coordination
- Events, Incidents, Weather, & Construction
- Alerts

## ► Reporting

- Prioritize signal needs
- Communicate system status to region/senior leaders and public

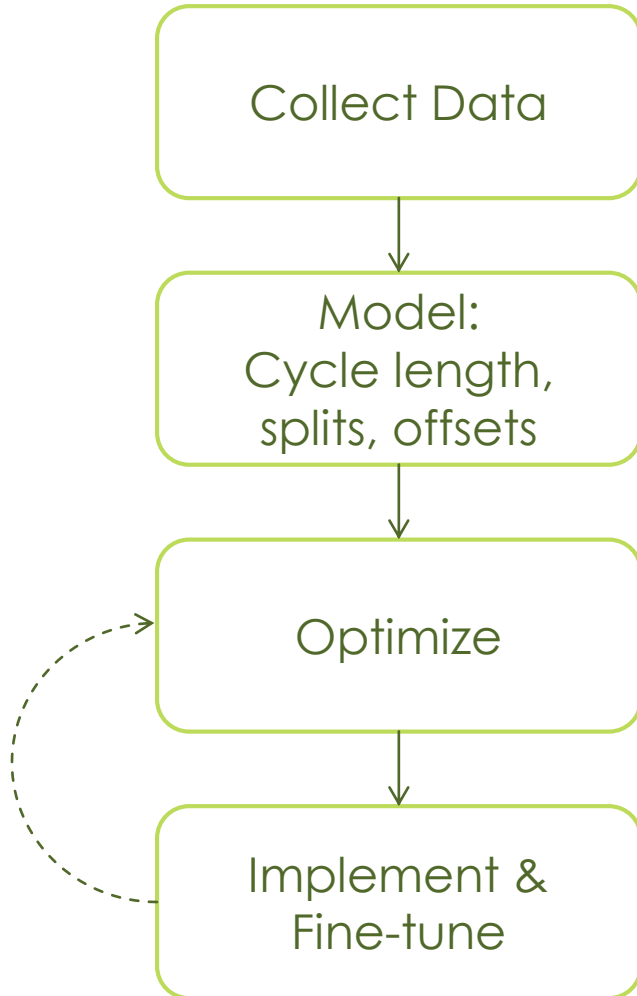
## ► Modeling/planning

- Approach Volumes
- Turning Movement Counts
- Speed

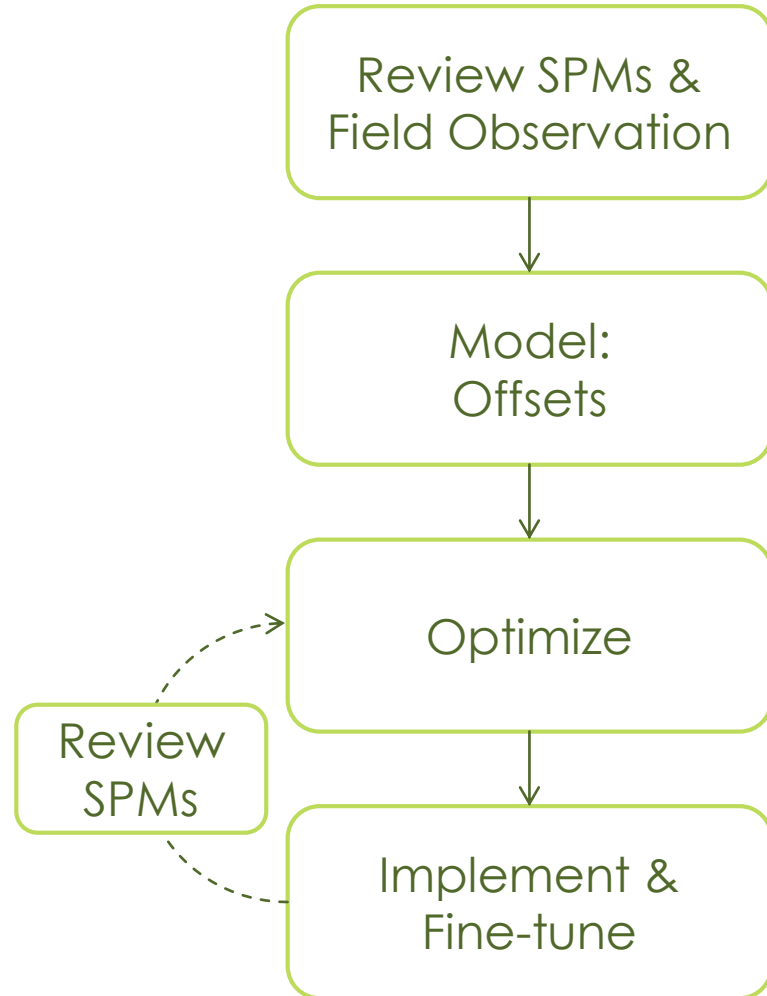


# Optimization with SPMs

## Traditional Process

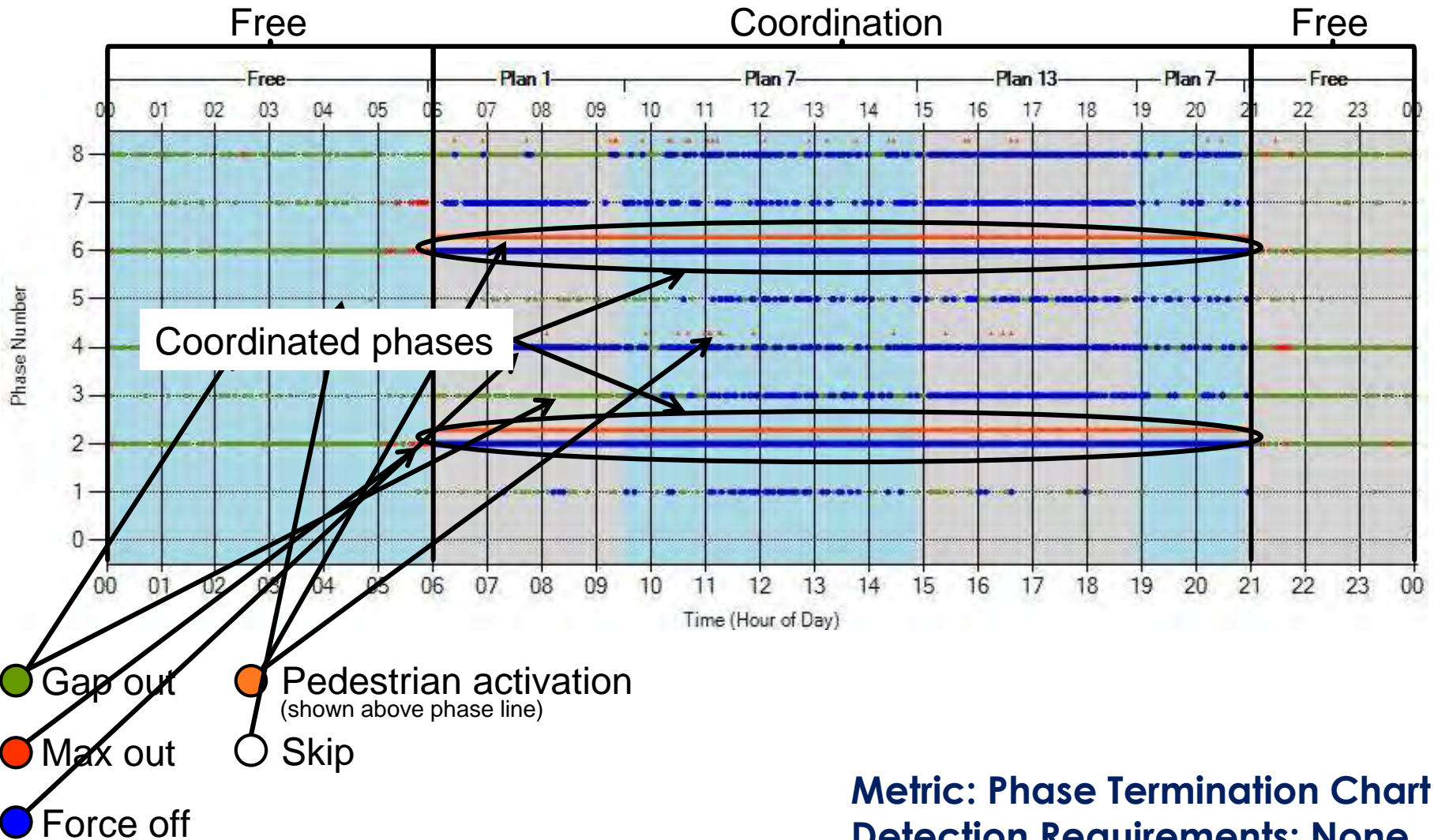


## Modified Process with SPMs



# Normal Intersection Example: Phase Termination Chart

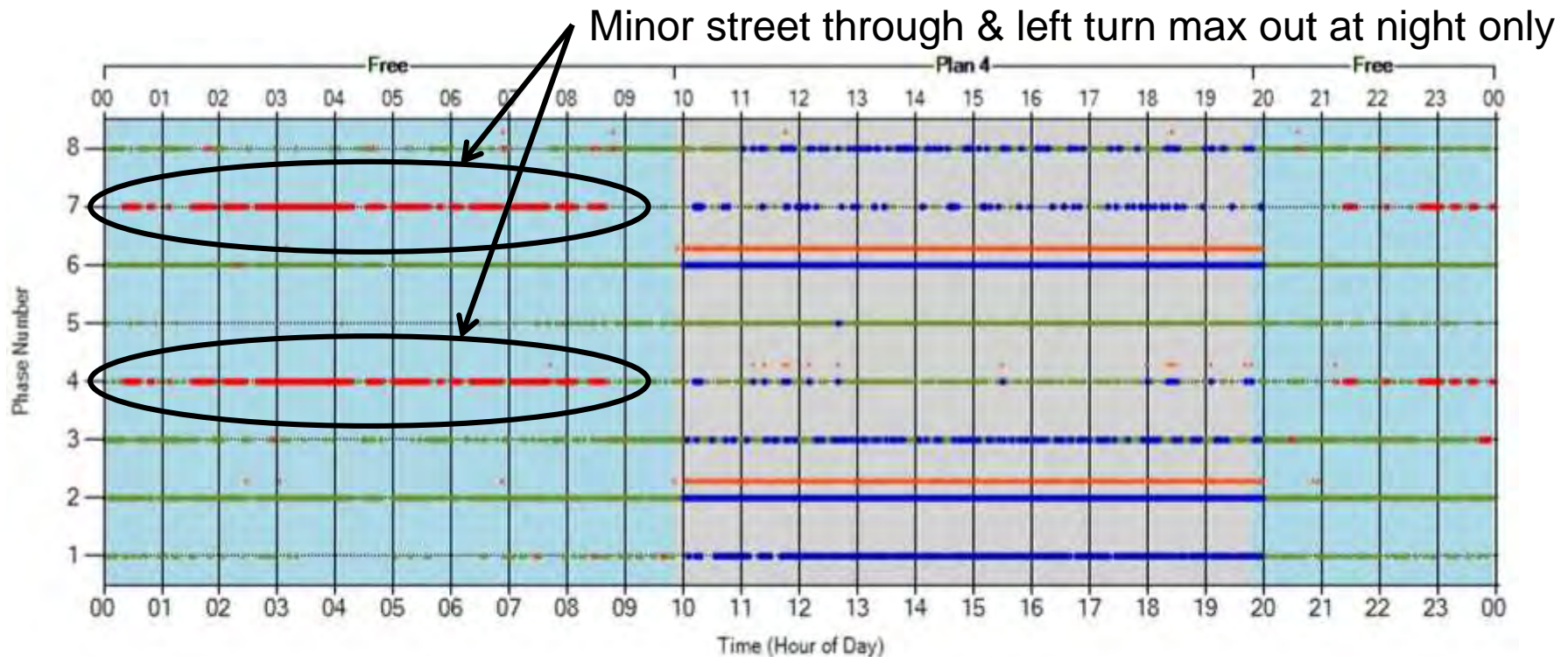
- 8-phase signal with working detection



**Metric: Phase Termination Chart**  
**Detection Requirements: None**

# Maintenance Example: Nighttime detection problem

- BEFORE: Video detection not working at night



- Gap out
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

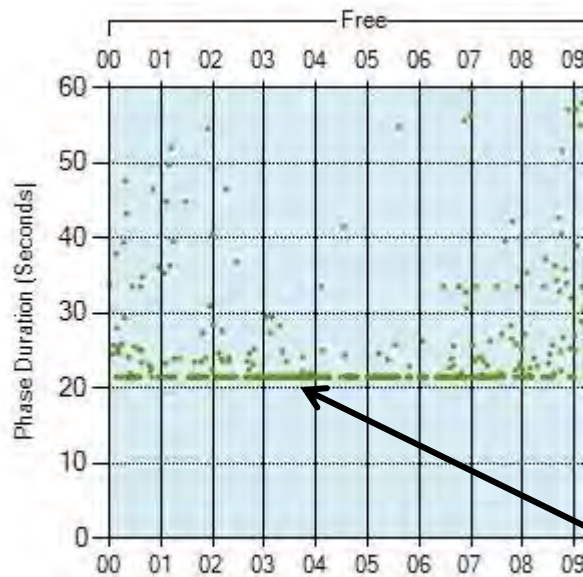
**Metric: Purdue Phase Termination**  
**Detection Requirements: None**



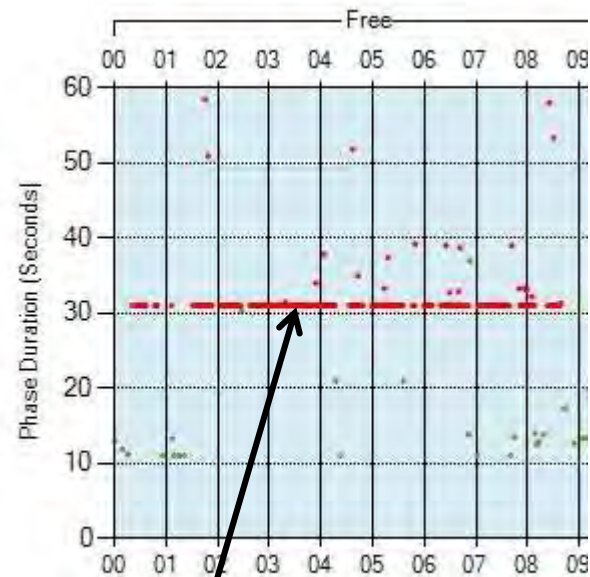
# Maintenance Example: Nighttime detection problem

- BEFORE: Video detection not working at night

Major Street (Ø2)



Minor Street (Ø4)



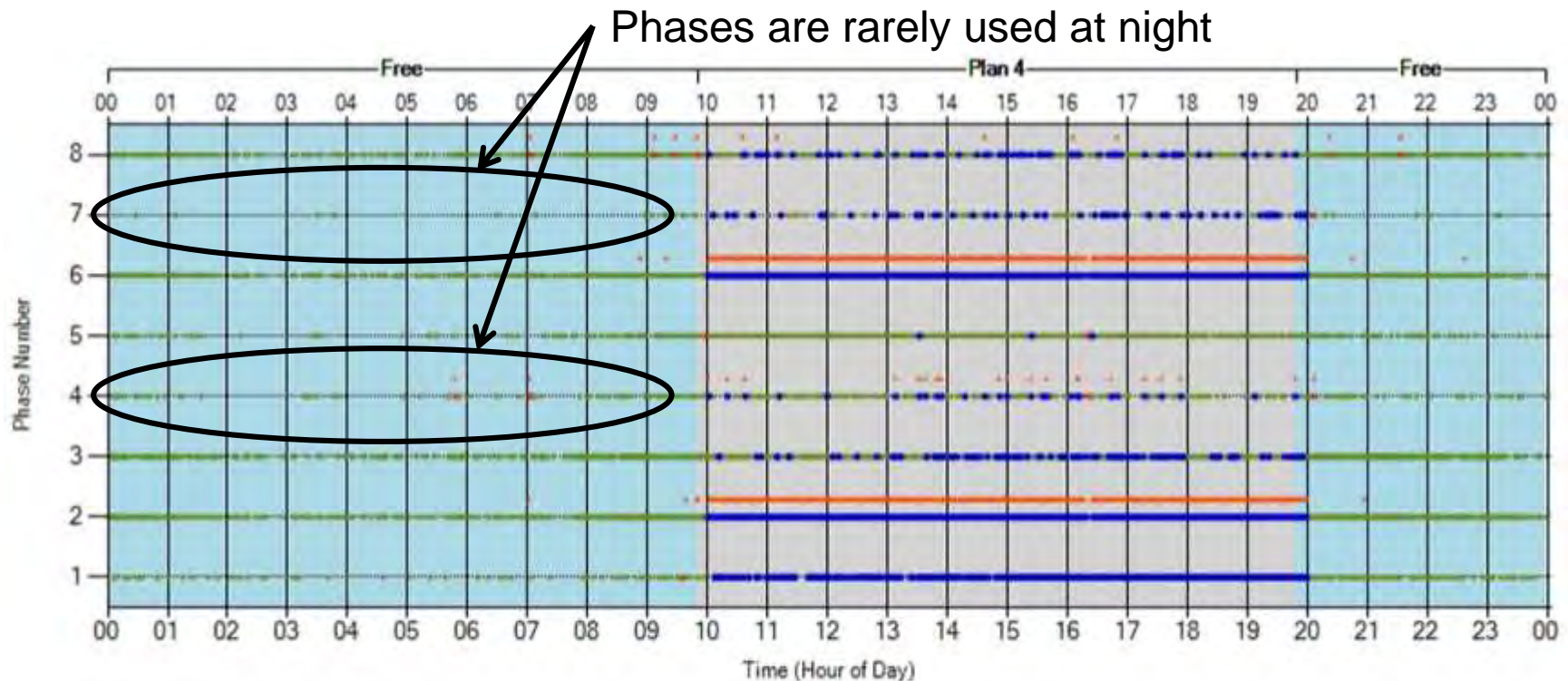
Major Street sees 20s of green and 30s of red.

- Gap out
- Pedestrian activation  
(shown above phase line)
- Max out
- Skip
- Force off

**Metric: Split Monitor**  
**Detection Requirements: None**

# Maintenance Example: Nighttime detection problem

- AFTER: New detection technology installed



- Gap out
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Purdue Phase Termination**  
**Detection Requirements: None**

# Alert Example: 100% Max Out



## SPM Alerts for 4/9/2014

 SPMWatchDog@utah.gov

5092 - SR-126 (1900 W) & Riverdale (5300 S) (Roy) - Phase: 1  
5105 - Antelope (SR-108/2000 N) & I-15 NB (Layton) - Phase: 4  
6022 - US-89 & Pacific Dr (American Fork) - Phase: 3  
6305 - 400 East & 800 North - Phase: 4  
6310 - Center Street (Orem) & I-15 SPUI - Phase: 8  
7055 - Bangerter Hwy (SR-154) & SR-201 DDI - Phase: 5  
7062 - Bangerter Hwy (SR-154) & 4700 South - Phase: 11  
7613 - 10600 South & 700 West - Phase: 8  
8114 - Bluff Street & I-15 NB Ramps - Phase: 4

Example

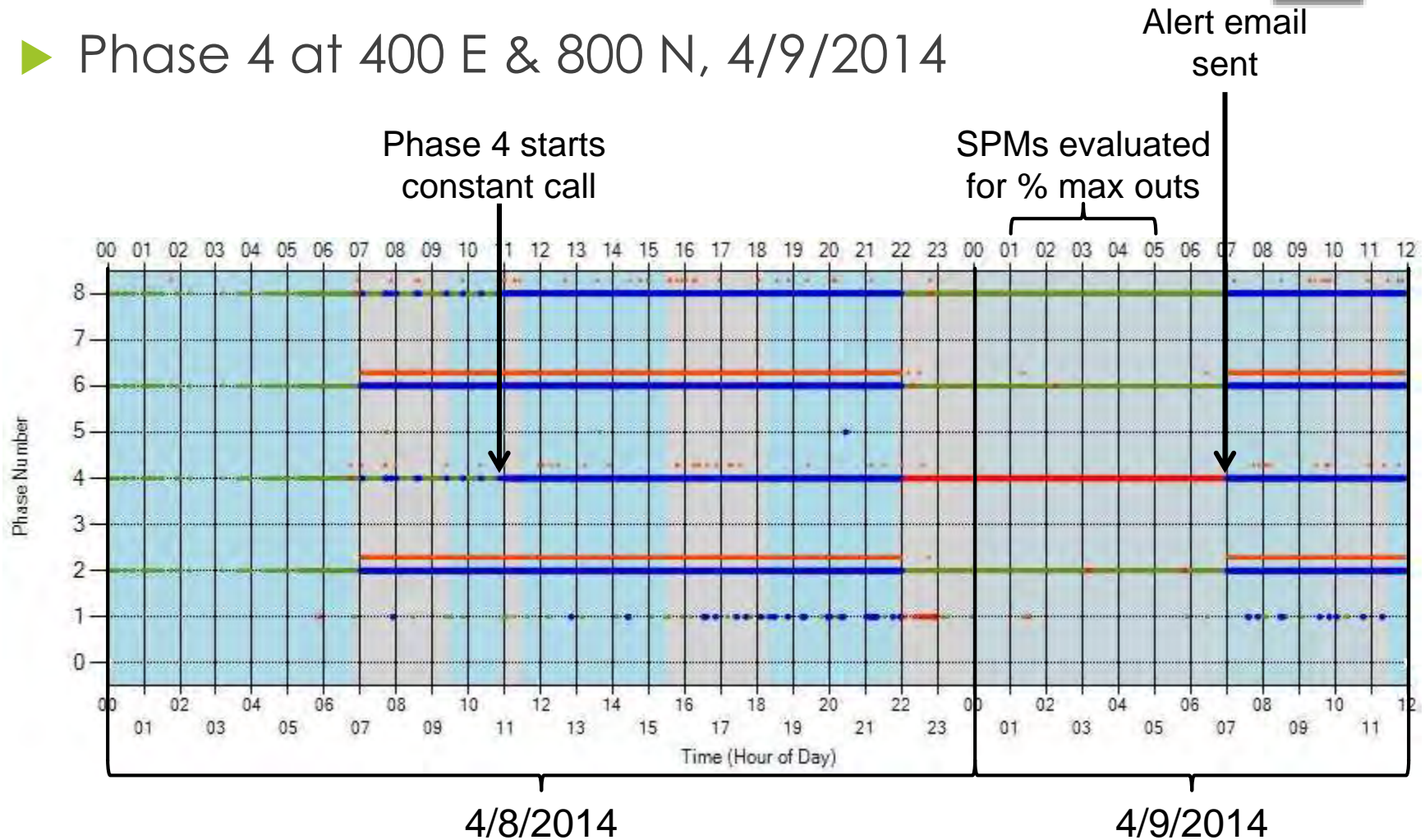
- ▶ Daily email at 7 a.m.
- ▶ Uses Purdue Phase Termination chart data
- ▶ Flags phases with >90% max-outs on each phase between 1 a.m. and 5 a.m.
- ▶ Compare to previous day's list. Only phases with new flags are sent in the email.

**Metric: Purdue Phase Termination**  
**Detection Requirements: None**



# Alert Example: 100% Max Out

► Phase 4 at 400 E & 800 N, 4/9/2014

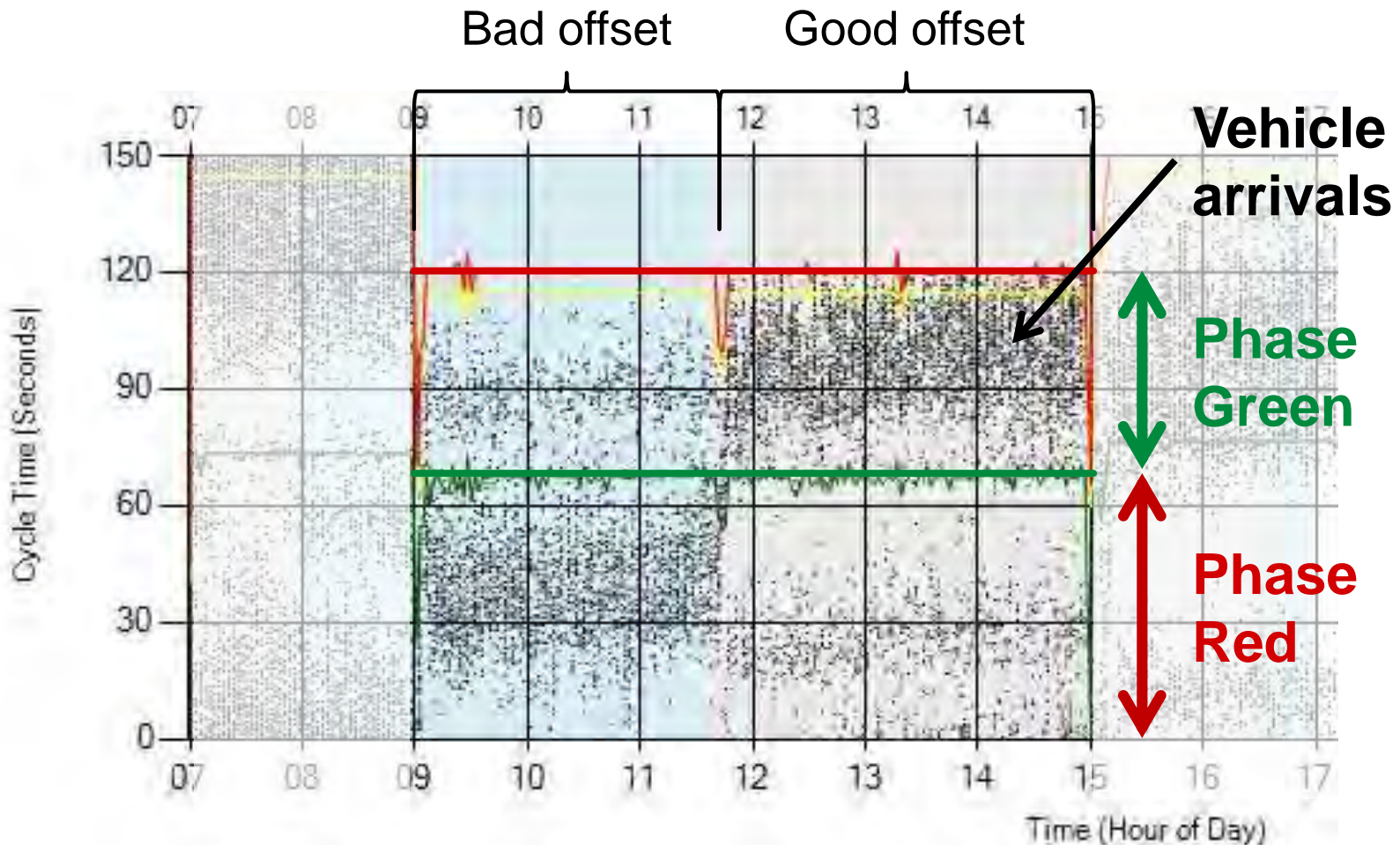


- Gap out
- Pedestrian activation (shown above phase line)
- Max out
- Skip
- Force off

**Metric: Purdue Phase Termination**  
**Detection Requirements: None**

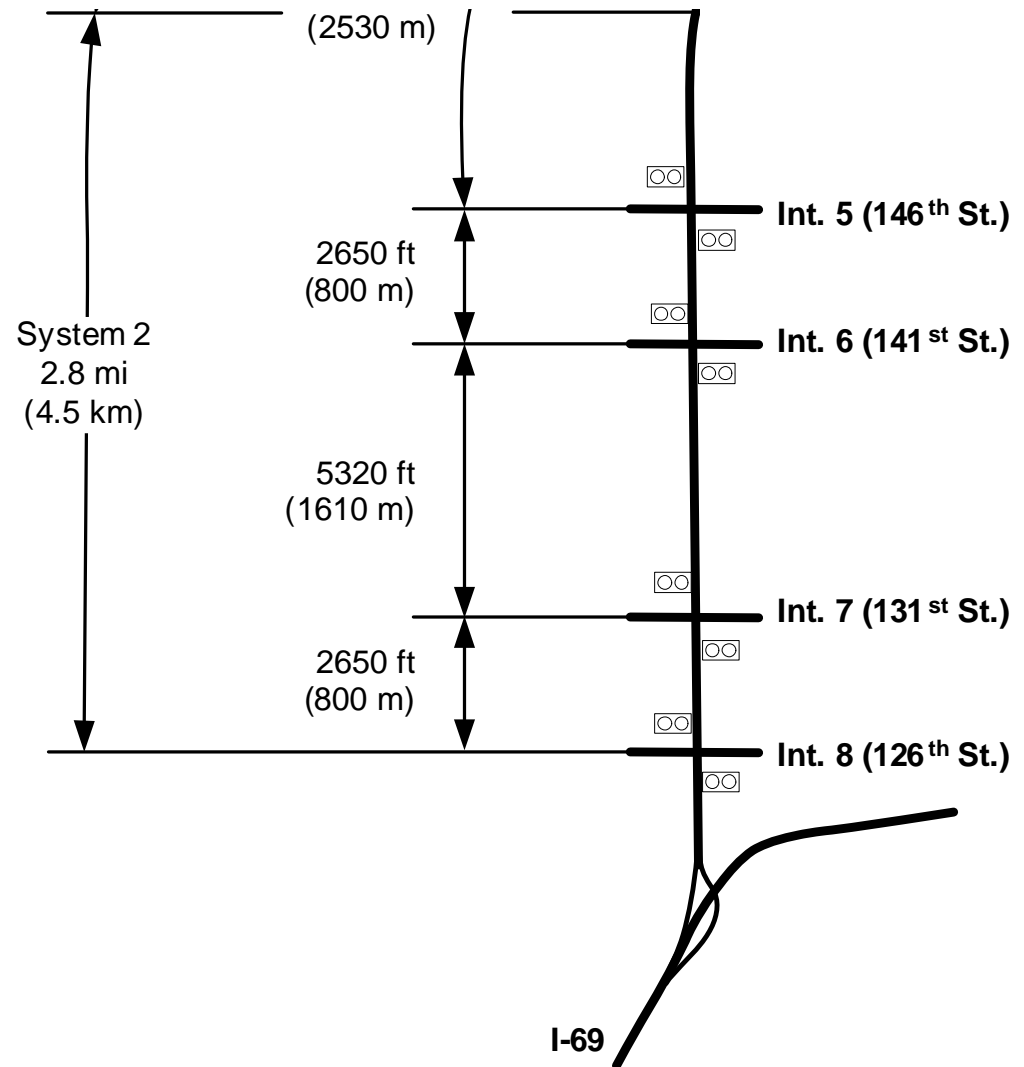
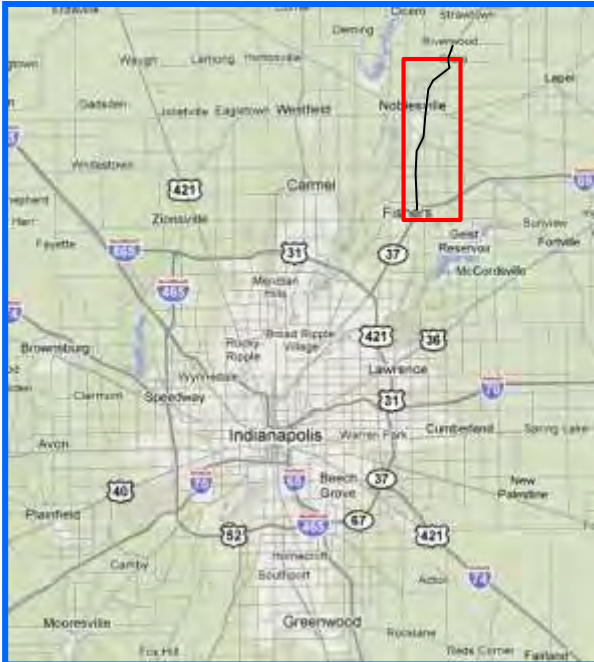
# Optimization Example: Progression Quality

- Fine-tuning new coordination plans



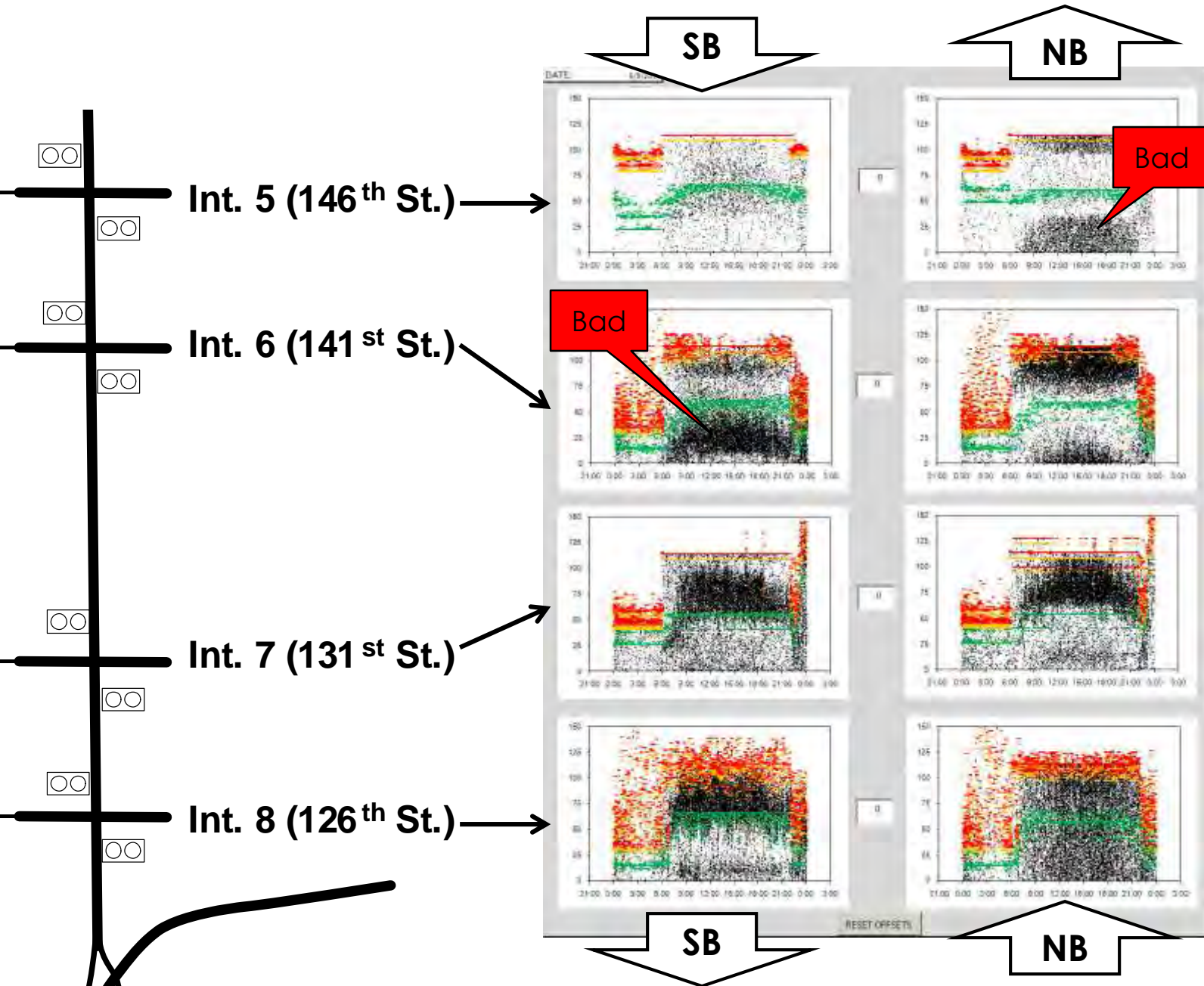
**Metric: Purdue Coordination Diagram**  
**Detection Requirements: Advance**

# Offset Optimization Case Study

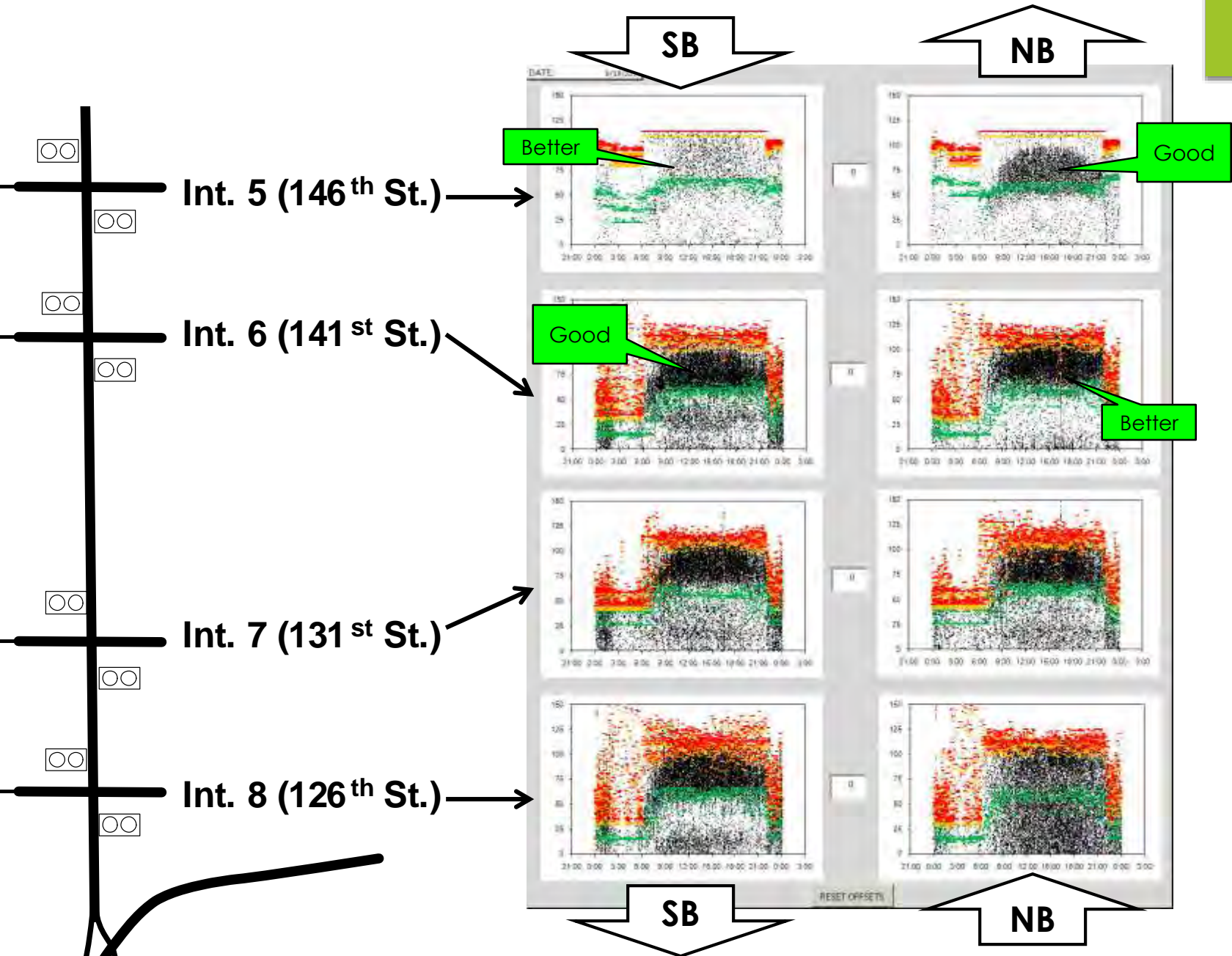


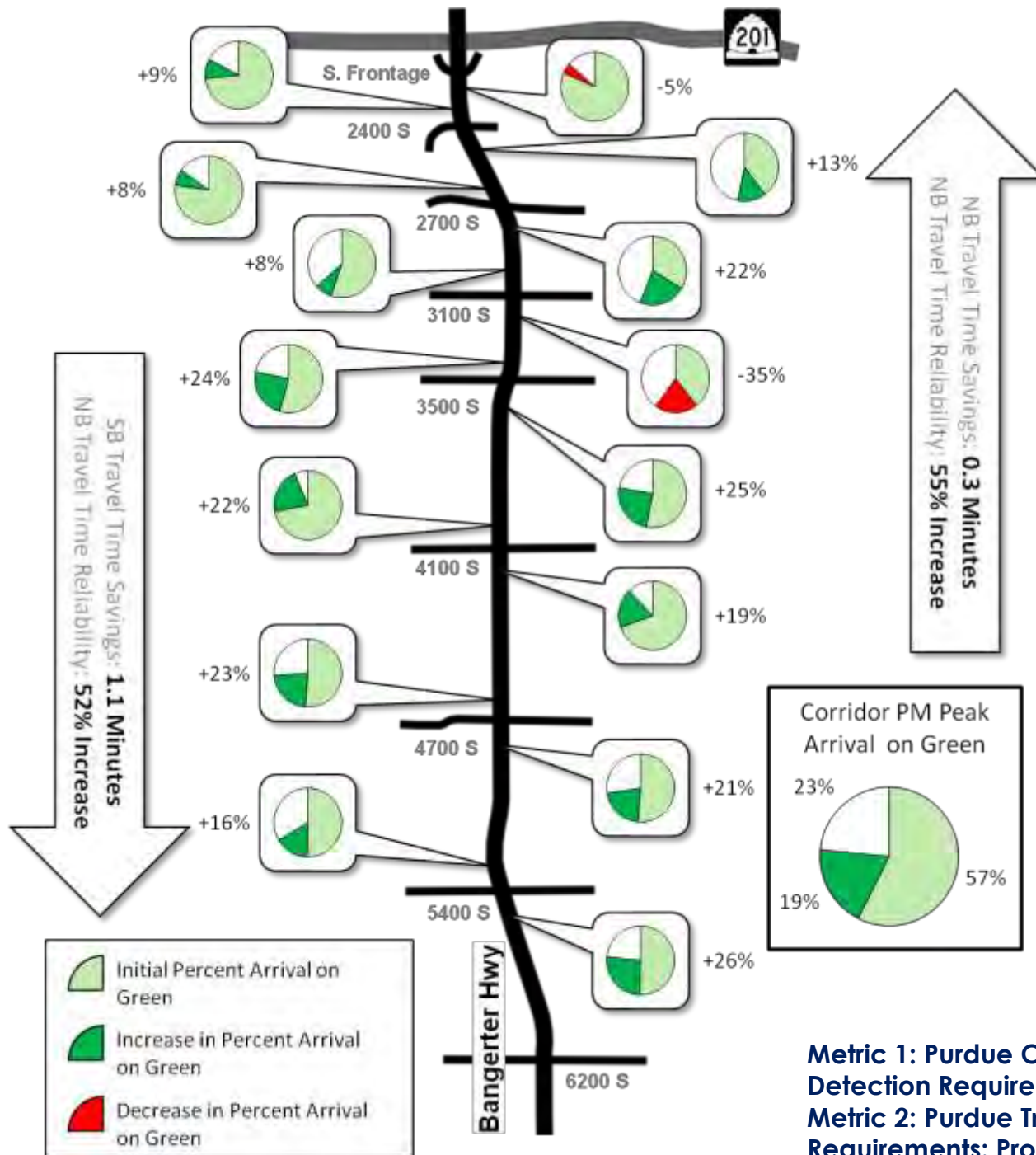


# Offset Optimization - BEFORE



# Offset Optimization – AFTER





**Metric 1: Purdue Coordination Diagram**  
**Detection Requirements: Advance**  
**Metric 2: Purdue Travel Time Diagram**  
**Requirements: Probe data set**



# Metrics & Detection Requirements

## Controller high-resolution data only

Purdue Phase Termination  
Split Monitor

## Advanced Count Detection (~400 ft behind stop bar)

Purdue Coordination Diagram  
Approach Volume  
Platoon Ratio

Arrivals on Red  
Approach Delay  
Executive Summary Reports

## Advanced Detection with Speed

Approach Speed

## Lane-by-lane Count Detection

Turning Movement Counts

## Lane-by-lane Presence Detection

Split Failure (future)

## Probe Travel Time Data (GPS or Bluetooth)

Purdue Travel Time Diagram



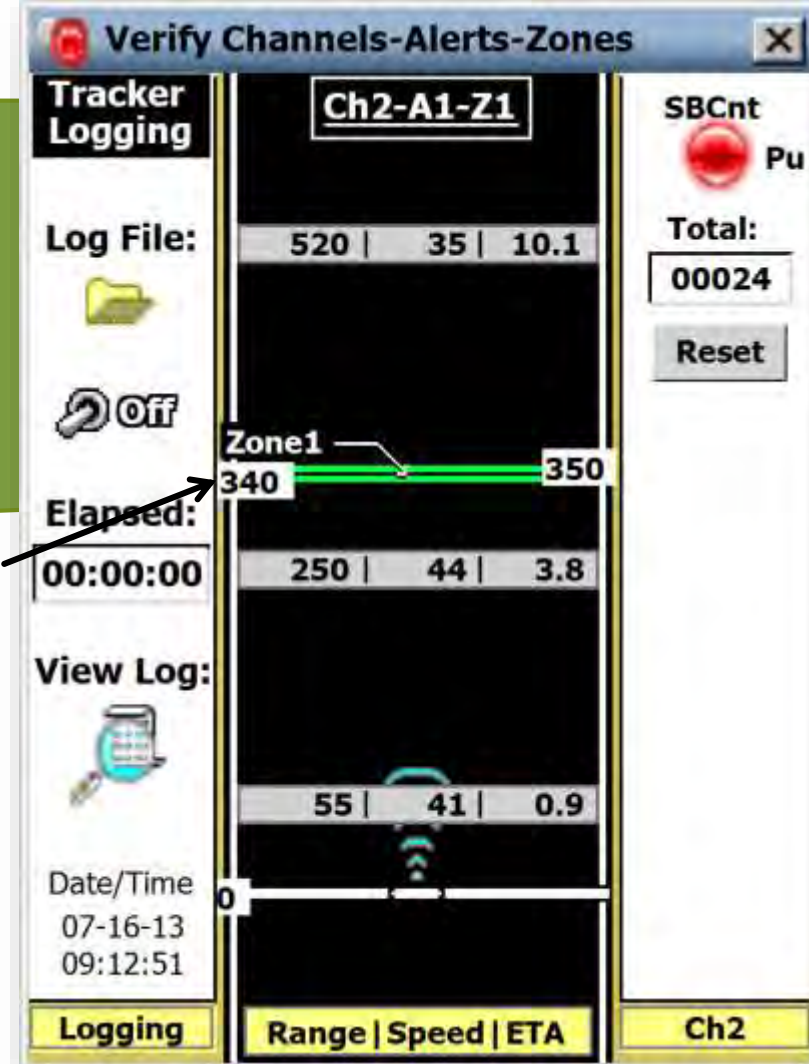


# Setback Count Detectors

## Wavetronix Advance

- ▶ Used to timestamp vehicle arrivals
- ▶ 10' count zone placed ~350' behind stop bar
- ▶ No additional expense if already in place for dilemma zones
- ▶ May undercount dense traffic

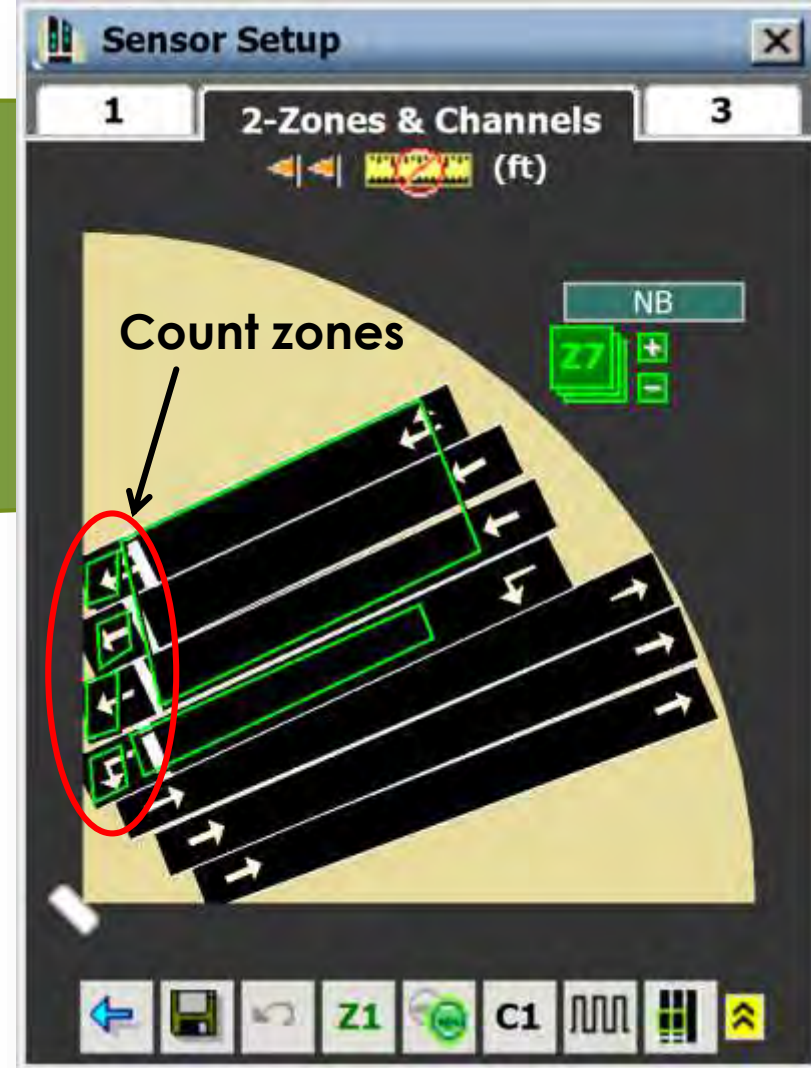
Count zone



# Stop Bar Count Detectors

## Wavetronix Matrix

- ▶ Used for turning movement counts
- ▶ Lane-by-lane detection zones in front of stop bar
- ▶ Requires detection rack card for every two zones (\$\$\$\$\$\$) or Click 650 Detector BIU





# Automated Traffic Signal Performance Measures

## Technology Implementation Group: 2013 Focus Technology

<http://tig.transportation.org>

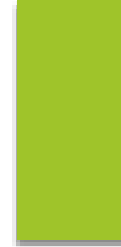
Mission: Investing time and money to accelerate technology adoption by agencies nationwide





# Find out more:

<http://tig.transportation.org>



## AASHTO TIG

- [TIG Home](#)
- [About TIG](#) ▶
- [Focus Technologies](#)
- [Executive Committee](#) ▶
- [Feedback](#)
- [Additionally Selected Technologies](#)
- [TIG-Solicitation](#)
- [Lead States Team Guidance](#) ▶

## TIG Home

[AASHTO](#) > [AASHTO Technology Implementation Group](#) > [TIG Home](#)

AASHTO's Technology Implementation Group — or TIG — scans the horizon for outstanding technology and invests time and money to accelerate their adoption by agencies nationwide.

Each year, TIG selects a highly valuable, but largely unrecognized procedure, process, software that has been adopted by at least one agency, is market ready and is available for use by other agencies.

Guided by the vision of "a culture where rapid advancement and implementation of high payoff, expectation of the transportation community," TIG's objective is to share information with AASHTO agencies, and their industry partners to improve the Nation's transportation system.

Recently selected technologies with links to additional information are listed below. Also, you may find [Additionally Selected Technologies](#) categorized by AASHTO subcommittee interest area.

### Lead States Team Focus Technologies

#### 2013 Focus Technologies



- [Automated Traffic Signal Performance Measures](#)
- [UPlan Phase II](#)

#### Prior Four Years Focus Technologies

- [Embedded Data Collector](#)
- [Environmental Planning GIS Tools](#)

### Additionally Selected Technologies

#### 2013 ASTs

- [Double Crossover Diagonal](#)

#### Prior Four Years ASTs

- [Anonymous Wireless Time Data Collection](#)
- [Curvature Extension](#)

# Additional Information

## UDOT Signal Performance Metrics

<http://udottraffic.utah.gov/signalperformancemetrics>

## Purdue/INDOT JTRP Report →

<http://tinyurl.com/signalmoie>

## AASHTO TIG

<http://tig.transportation.org>

